

# Computing Principal Components with the Eigen-decomposition of a Low Dimensional Matrix

Tony X. Han

Electrical & Computer Engineering Department  
University of Missouri

When we do PCA, we need to do an eigen-decomposition of the covariance matrix. Suppose the  $m$  sample data we have are:  $\tilde{\mathbf{x}}_i, i = 1, \dots, m$ .  $\tilde{\mathbf{x}}_i$ 's are usually vectorized image with dimension of  $N \times 1$ . For example, if you want to convert an image with resolution of  $300 \times 200$  to a vector, the  $N = 300 \times 200 = 60\,000$ , which is much larger than the number of data sample  $m$ . So, usually  $N \gg m$ . The procedure of PCA is as follows:

1. Compute the mean:

$$\bar{\mathbf{x}} = \frac{1}{m} \sum_{i=1}^m \tilde{\mathbf{x}}_i. \quad (1)$$

2. Generate the zero-mean data matrix:

$$\mathbf{x}_i = \tilde{\mathbf{x}}_i - \bar{\mathbf{x}}. \quad (2)$$

$$\mathbf{A} = ( \mathbf{x}_1 \quad \mathbf{x}_2 \quad \dots \quad \mathbf{x}_m ) \quad (3)$$

3. Construct the covariance matrix:

$$\mathbf{C} = \mathbf{A}\mathbf{A}^T \quad (4)$$

The covariance matrix  $\mathbf{C}$  is symmetric and positive definite. So the eigenvalues of  $\mathbf{C}$  is real and non-negative.

4. Eigen-decomposition:

The eigenvalues  $\lambda_i$ 's and the eigenvectors  $\mathbf{v}_i$ 's of  $\mathbf{C}$  satisfy

$$\mathbf{C}\mathbf{v}_i = \lambda_i\mathbf{v}_i. \quad (5)$$

Here we assume that the eigenvector is normalized, i.e.,  $\|\mathbf{v}_i\|_2 = 1$ . Writing Eq. (5) in the matrix form, we have

$$\mathbf{C}\mathbf{V} = \mathbf{V}\mathbf{\Lambda}, \quad (6)$$

where

$$\mathbf{\Lambda} = \begin{pmatrix} \lambda_1 & 0 & 0 & \dots \\ 0 & \lambda_2 & 0 & \dots \\ & & \ddots & \\ 0 & \dots & 0 & \lambda_N \end{pmatrix} \quad (7)$$

is the diagonal matrix with the eigenvalues  $\lambda_i$ 's in the diagonal. In the PCA procedure, we put  $\lambda_i$ 's in  $\mathbf{\Lambda}$  with the descent order, i.e.,  $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_N$ .  $\mathbf{V}$  is the matrix consists of the eigenvectors corresponding to  $\lambda_i$ 's.

$$\mathbf{V} = (\mathbf{v}_1 \quad \mathbf{v}_2 \quad \dots \quad \mathbf{v}_N). \quad (8)$$

So we have the eigen-decomposition of the covariance matrix:

$$\mathbf{C} = \mathbf{V}\mathbf{\Lambda}\mathbf{V}^{-1} = \mathbf{V}\mathbf{\Lambda}\mathbf{V}^T. \quad (9)$$

The reason that  $\mathbf{V}^T = \mathbf{V}^{-1}$  is due to the fact that  $\mathbf{C}$  is symmetric and positive definite [1].

5. Construct the projection matrix  $\mathbf{P}$ :

In order to apply PCA for dimension reduction, we can pick a number  $k < N$  to form the projection matrix from the first  $k$  principal components as

$$\mathbf{P} = \begin{pmatrix} \mathbf{v}_1^T \\ \mathbf{v}_2^T \\ \vdots \\ \mathbf{v}_k^T \end{pmatrix}. \quad (10)$$

To represent a sample  $\mathbf{x}_i$  of high dimension ( $N \times 1$ ), we use its low dimensional projection  $\mathbf{z}_i$  ( $k \times 1$ ), i.e.

$$\mathbf{z}_i = \mathbf{P}\mathbf{x}_i. \quad (11)$$

If  $N$  is not very big, we can use the procedure mentioned above to compute the principal components. But for our eigen-background modeling case [2],  $N$  is usually more than 40 000. It is infeasible for us to construct the covariance matrix with the dimension  $N \times N$ . In our eigen-background modeling scenario, the number of data sample  $m$  is the number of image frames of the training sequence.  $m$  usually ranges from 20 to 300. So  $m \ll N$  here.

Let us consider the matrix  $\mathbf{D} = \mathbf{A}^T\mathbf{A}$ , which is a  $m \times m$  matrix. This is a very small matrix comparing with  $\mathbf{C}$ .

The eigenvalues  $\tilde{\lambda}_i$ 's and the eigenvectors  $\tilde{\mathbf{v}}_i$ 's of  $\mathbf{D}$  satisfy

$$\mathbf{A}^T\mathbf{A}\tilde{\mathbf{v}}_i = \tilde{\lambda}_i\tilde{\mathbf{v}}_i. \quad (12)$$

We want to explore the relationships among the eigenvalues and eigenvectors of  $\mathbf{A}^T\mathbf{A}$  and  $\mathbf{A}\mathbf{A}^T$ . Left multiply  $\mathbf{A}$  at the both side of Eq. (12), we have

$$\mathbf{A}\mathbf{A}^T\mathbf{A}\tilde{\mathbf{v}}_i = \tilde{\lambda}_i\mathbf{A}\tilde{\mathbf{v}}_i. \quad (13)$$

i.e.,

$$\mathbf{C}\mathbf{A}\tilde{\mathbf{v}}_i = \tilde{\lambda}_i\mathbf{A}\tilde{\mathbf{v}}_i. \quad (14)$$

We conclude that  $\tilde{\lambda}_i$  is an eigenvalue of  $\mathbf{C}$ , with the corresponding eigenvector  $\mathbf{A}\tilde{\mathbf{v}}_i$ .

Similarly, left multiply  $\mathbf{A}^T$  at the both side of Eq. (5), we have

$$\mathbf{A}^T\mathbf{A}\mathbf{A}^T\mathbf{v}_i = \lambda_i\mathbf{A}^T\mathbf{v}_i. \quad (15)$$

i.e.,

$$\mathbf{D}\mathbf{A}^T\mathbf{v}_i = \lambda_i\mathbf{A}^T\mathbf{v}_i. \quad (16)$$

So  $\lambda_i$  is an eigenvalue of  $\mathbf{D}$ , with the corresponding eigenvector  $\mathbf{A}^T\mathbf{v}_i$ . Both  $\mathbf{A}\mathbf{A}^T$  and  $\mathbf{A}^T\mathbf{A}$  are symmetric and positive definite matrix. So Eq.s (14) and (16) shows that  $\mathbf{A}\mathbf{A}^T$  and  $\mathbf{A}^T\mathbf{A}$  have exactly same set of eigenvalues. For the corresponding eigenvectors, we can establish a bijection between  $\mathbf{v}_i$ s and  $\tilde{\mathbf{v}}_i$ s using Eq.s (14) and (16). They are mapped to each other by:

$$\mathbf{v}_i = \mathbf{A}\tilde{\mathbf{v}}_i \quad (17)$$

and

$$\tilde{\mathbf{v}}_i = \mathbf{A}^T\mathbf{v}_i. \quad (18)$$

There is an interesting question. Since the dimension of  $\mathbf{A}\mathbf{A}^T$  ( $N \times N$ ) is much larger than the one of  $\mathbf{A}^T\mathbf{A}$  ( $m \times m$ ), how can they have the same amount of eigenvalues and eigenvectors?

That is because  $\text{rank}(\mathbf{A}\mathbf{A}^T) = \text{rank}(\mathbf{A}^T\mathbf{A}) = \text{rank}(\mathbf{A})$ . So they have exactly same amount of non-zero eigenvalues and the eigenvectors corresponding to the non-zero eigenvalues. The principal components are eigenvectors corresponding to the largest  $k$  eigenvalues. So we can compute the principal components of  $\mathbf{A}\mathbf{A}^T$  using the eigen-decomposition of  $\mathbf{A}^T\mathbf{A}$ . The eigen-decomposition of  $\mathbf{A}^T\mathbf{A}$  can be further simplified by Singular Value Decomposition (SVD). We can simply compute the SVD of  $\mathbf{A}$ . Refer to page 369-372 of [3] for details.

## References

- [1] G. Strang, *Linear Algebra and its Applications*. San Diego: Harcourt Brace Jonanovich, 3rd ed., 1988.
- [2] N. Oliver, B. Rosario, and A. Pentland, "A bayesian computer vision system for modeling human interactions," *Pattern Analysis and Machine Intelligence, IEEE Transactions on*, vol. 22, pp. 831–843, Aug 2000.
- [3] T. K. Moon and W. C. Stirling, *Mathematical methods and algorithms for signal processing*. 2000.