Is the Shanxi rift of northern China extending?

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[1] The Shanxi rift in northern China is marked by intensive seismicity, including many devastating historic earthquakes. Geological and seismological evidence show 0.5–1.6 mm/yr extension across the rift, and previous GPS results indicated an extension rate of 4 ± 2 mm/yr. We show here newly compiled GPS data that indicate coherent crustal motion and no clear sign of extension across the rift. We reconcile the discrepancy between geological observations and GPS results in a simple viscoelastic finite element model with timescale-dependent crustal deformation. The GPS velocities can be fit by a model with a near elastic upper crust, consistent with predominantly interseismic deformation. The geological rate of extension is predicted when viscous creep of the crust is dominant, driven by the gravitational potential energy arising from the heterogeneity of crustal structure. INDEX TERMS: 1208 Geodesy and Gravity: Crustal movements—intraplate (8110); 8107 Tectonophysics: Continental neotectonics; 8109 Tectonophysics: Continental tectonics—extensional (0905); 8122 Tectonophysics: Dynamics, gravity and tectonics; 8159 Tectonophysics: Rheology—crust and lithosphere.

1. Introduction

[2] The Shanxi rift in northern China is an intracontinental rift zone with many devastating earthquakes, including the 23 January 1556 Huaxian earthquake (M ≥ 8), the most deadly earthquake in human history that killed ~830,000 people [Ming et al., 1995]. Chinese historic records show at least 32 earthquakes with magnitude ≥6 occurred within the rift since 231 AD (Figure 1) [Ming et al., 1995]. Modern seismicity indicates active rifting (Figure 1). Wesnosky et al. [1984] estimated a coseismic extension rate around ~1.0 mm/yr based on seismic moment data. This is close to the 0.5–1.6 mm/yr extension rate averaged over the Late Pliocene-Quaternary time [Zhang et al., 1998].

[3] Given the potential of earthquake hazard in the Shanxi rift and adjacent regions, several Chinese agencies have conducted a series of Global Positioning System (GPS) field campaigns since 1992. The earlier results indicated 4 ± 2 mm/yr active extension across the Shanxi rift [Shen et al., 2000]. However, the velocity jump across the Shanxi rift became obscure when more GPS data were compiled [Wang et al., 2001a].

[4] Is the Shanxi rift extending? We address this question by first presenting the newly compiled GPS results. We then reconcile the apparently discrepant GPS, seismological, and geological data using a simple geodynamic model that simulates crustal deformation at different timescales.

2. Geological Background and GPS Results

[5] The Shanxi rift, bordered by the Ordos Massif to the west and the Taihang Shan Uplift to the east, is located within the North China Block, which is part of the Sino-Korean Achaean shield that became reactivated since late Mesozoic [Griffin et al., 1998] (Figure 1). Extension of the Shanxi rift may have started in Miocene [Zhang et al., 1998], but the present graben formed mainly since Pliocene [SSBRG, 1988; Xu et al., 1993].

[6] The GPS data collected by the China Seismological Bureau during 1992–1996 indicated 4 ± 2 mm/yr extension across the Shanxi rift [Shen et al., 2000]. An expanded data set, however, showed more scattering of the GPS site velocities; the signals of active extension vanished [Wang et al., 2001a]. To resolve the discrepancies between these datasets, we have compiled the latest GPS data with 447 site velocities measured in 1999 and 2001 by the First Crustal Deformation Monitoring Center (FCDMC) of China Seismological Bureau. The measurements were made with Ashtech Z-12 receivers. The data processing was the same as reported by Shen et al. [2000]. We used the GAMIT software to obtain loosely constrained daily solutions for the station positions and satellite orbits. The data were then combined with 16 global IGS solutions produced by the Scripps Orbital and Position Analysis Center (SOPAC) using the GLOCK software to get the commonly shared parameters. The final station positions and site velocities were derived using the QOCA software in the ITRF2000 reference frame.

[7] The new data are plotted together with previously published datasets under the same confidence level. Because the data of Wang et al. [2001a] were processed differently from Shen et al. [2000] and this study, we only compare with the dataset from Shen et al. [2000]. Figure 2a shows no clear sign of active extension across the Shanxi rift, consistent with the results of Wang et al. [2001a]. In Figure 2b, we plotted the new GPS data onto the same profile used in Shen et al. [2000]. It shows that the velocity jump across...
the Shanxi rift reported in Shen et al. [2000] vanished in the expedned dataset.

3. Reconcile the Discrepant Observations

[8] The 1991 Datong earthquake (M \sim 6.1) located in the northern part of the Shanxi rift (Figure 1), an area covered during the 1992–1996 GPS measurements [Shen et al., 2000], may have affected the velocity of some of the sites near the epicenter, but the post-seismic creep was unlikely to affect most of the GPS stations covering the entire North China Block. Although intrinsic errors of the present GPS data could have contributed to the discrepancy between the different datasets, the lack of clear signs of active extension across the entire length of the Shanxi rift may be better explained by the timescale-dependent crustal deformation [Liu et al., 2000a].

[9] Since the 1991 Datong earthquake, there have been only two moderate events (M \sim 6) near the northern edge of the North China Block and no large earthquakes within the Shanxi rift, thus the GPS data reflect largely interseismic deformation across the Shanxi rift when most of the faults remain locked. We developed a simple geodynamic model to simulate crustal deformation at two timescales: the short-term interseismic deformation represented by the GPS data, and the long-term deformation reflected in the geological observations and to some extend in the accumulated earthquake data. The model is two-dimensional (Figure 3a), based on the TECTON finite element codes [Melosh and Raefsky, 1981] and assumes a viscoelastic rheology. The top of the model is a free surface with simplified topography. The Winkler springs are used on density boundaries (the reference surface, defined at the Eastern Plain, and the base of the crust) to simulate restoring forces [Williams and Richardson, 1991]. The present GPS data indicates a weak ESE compression over the entire North China Block (see Figure 2 and Wang et al. [2001a]). We use 8.7 mm/yr in the Ordos massif and 7.0 mm/yr in the Eastern Plain, all with respect to stable Eurasia, as the velocity boundary condition.

[10] If aseismic creep is negligible, the simplest way to simulate the interseismic crustal deformation with all active faults locked is to assume an elastic upper crust. The resulting surface velocity field is close to a linear interpo-

Figure 1. Major faults and seismicity in the Shanxi rift and surrounding region. The inset shows the plate tectonic setting. Thrust and normal faults are represented by the teeth line and ball-head line, respectively. The shaded circles are historic earthquakes (M \geq 6.0). Small dots are earthquakes (M \geq 3) from 1973–2003. Focal mechanism solutions are for selected modern earthquakes (M \geq 4) [http://www.seismology.harvard.edu; Zhang et al., 1990]. Events 1, 2, and 3 are the 1991/03/26 M = 6.1 Datong, 1996/05/03 M = 6.6 Baotou and 1998/01/10 M = 6.2 Zhangbei earthquakes, respectively. SCB, South China Block; QL, the Qinling orogen; TLF, the Tan-Lu fault; HG, the Hetao graben.

Figure 2. (a) GPS residual velocities around the Shanxi rift with respect to the Xi’an permanent GPS station within the NUVEL-1A reference frame. Error ellipses represent 95% confidence level. The velocities with shaded error ellipses are from 1992 to 1996 [Shen et al., 2000]. Only selected sites were shown for clarity. Line A is the velocity profile in (b). Line B is the transect bases on which the numerical model shown in Figure 3a was built. (b) GPS site velocities relative to stable Eurasia, plotted along an ESE profile (location in (a)) within a 150 km wide swath. The square symbols are velocities from Shen et al. [2000] showing extension across the Shanxi rift. SR, the Shanxi rift; TU, the Taihang Shan Uplift; EP, the Eastern Plain.
lation of the applied boundary velocities, which fits the GPS velocities reasonably well (Figure 2). Similar results can be obtained by assuming a high (>10^25 Pa s) effective viscosity for the upper crust [Liu et al., 2000a].

To simulate long-term stress state and crustal deformation, we assumed a viscoelastic upper crust and a power-law fluid middle-lower crust with temperature and strain rate dependent viscosity [Williams and Richardson, 1991]. The values of rheological parameters for the Maryland diabase and the Westly granite [Kirby and Kronenberg, 1987] were used to approximate the lower and middle crust, respectively. Figure 3b shows the predicted non-lithostatic differential stresses (σ_{xx} - σ_{zz}) for a case with laterally homogeneous rheology. The cold color shows negative values (σ_{xx} < σ_{zz}), indicating extension; the warm colors indicate compression. (c) Predicted differential stress with a weaker rheology in the Shanxi rift and the Eastern Plain. Abbreviations are explained in Figure 2.

Figure 3. (a) Geometry and boundary conditions of the finite element model. The model surface is simplified from GTOPO-30 database, and the bottom approximates the Moho discontinuity [Ma, 1989; Xu et al., 1993]. See text for details. (b) Predicted differential stress (σ_{xx} - σ_{zz}) for a model with laterally homogeneous rheology. The cold color shows negative values (σ_{xx} < σ_{zz}), indicating extension; the warm colors indicate compression. (c) Predicted differential stress with a weaker rheology in the Shanxi rift and the Eastern Plain. Abbreviations are explained in Figure 2.

The real crustal rheology is certainly not uniform as assumed in Figure 3b. The surface heat flux within the Shanxi rift and many parts of the Eastern Plain is abnormally high [Hu et al., 2000]. In Figure 3c, we reduced the upper crustal viscosity from 7 \times 10^{24} to 3 \times 10^{24} Pa s in the Shanxi rift and the Eastern Plain, and increased the temperature by 20–40°C in the middle-lower crust under these two regions, effectively reducing the middle-lower crust viscosity to 10^{22} and 10^{21} Pa s. Whereas the general pattern of the predicted differential stress remains the same (Figure 3c), the extensional stresses are higher and more concentrated within the Shanxi rift than in Figure 3b.

Figure 4 shows the predicted surface velocity associated with the different cases of rheologic structures. The GPS data, which show a near linear trend of WNW-ESE
compression (curve A), can be fit by the interseismic model in which all the active faults are locked in the stiff upper crust (effective viscosity \( \sim 10^{23} \) Pa s) underlying by a viscous middle-lower crust (effective viscosities \( 10^{23} \sim 10^{22} \) Pa s) (curve B). At geological timescales, both the upper and lower crust deform as viscous media, and the predicted surface velocity shows extension in the Shanxi rift and compression in the Eastern Plain. The extension rate is \(<0.3 \text{ mm/yr}\) (curve C) for a laterally homogeneous crust as shown in Figure 3b. With a weaker rheology assumed for the Shanxi rift and the Eastern Plain as described in Figure 3c, the extension rate increases to \(~1.2 \text{ mm/yr}\) (curve D), similar to that derived from geological and seismological data [Wesnousky et al., 1984; Zhang et al., 1998]. Because the thermal-rheological structure is not well constrained, the exact values of the predicted extension rates need to be taken with caution.

4. Discussion and Conclusions

[14] We have shown that the previously reported GPS velocity change that indicate active extension of the Shanxi rift become obscure when more recent data are compiled. Although further measurements will reduce the uncertainties of the GPS data, a more significant explanation for the GPS data may be the timescale-dependent crustal deformation [Li et al., 2000a]. Measured over a short period (typically a few years), GPS data often reflect mainly interseismic deformation when the active faults remain locked. This explains the smooth GPS velocities over the Shanxi rift and many other regions of known active crustal deformation, such as the Central Andes [Kendrick et al., 2001; Leffler et al., 1997] and the Himalayan-Tibetan plateau [Wang et al., 2001a]. There may be transient strains near each individual fault associated with viscous relaxation in the ductile lower crust or aseismic creep on the faults, but dense and carefully designed GPS stations are needed to capture such subtle signals. On the other hand, seismological and geological data, representing crustal deformation over longer timescales, indicate that crustal extension in the Shanxi rift has been active. The cause of the Shanxi rift may be numerous and is debated [Yin, 2000]. Our results show that the gravitational potential energy arising from the heterogeneity of crustal thickness and thermal structure may be a major factor.

[15] GPS and other space-based geodetic measurements have been revolutionizing the studies of crustal deformation. However, given the timescale-dependence of rock rheology, it is important to understand how crust deforms at different timescales. The GPS data presented here cannot rule out active extension in the Shanxi rift. Given the history of devastating earthquakes in the Shanxi rift and the large population in the surrounding regions, continuous and carefully designed GPS measurements are needed to improve our understanding of the potential earthquake hazard.

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